

Numerical Fluid Dynamics

Atms 502, CSE 566

TUE., APR. 2, 2019

Images:

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ATMS 502 CSE 566

Tuesday, 2 April 2019

Class #21

Program #5 is due Tuesday, April 16

Plan for Today

• 1) Review

- Nonlinear instability and aliasing
- Quasi-compressible system
- 2) Semi-Lagrangian methods • Advantages, questions, choices
- 3) Program 5
 - 2-D quasi-compressible nonlinear flow

Semi-Lagrangian methods

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Semi-Lagrangian Methods

Ritchie et al. 1995

- "The <u>main motivation</u> for using a semi-Lagrangian formulation is to permit the use of time steps that far exceed the CFL stability criterion for the corresponding Eulerian model ... provided that the additional time truncation error does not significantly decrease the accuracy"
- Their case: 4x improvement in efficiency

Semi-Lagrangian Methods

• Generally:

- Eulerian view evolution at a point
- Lagrangian view following fluid motion
- o *Semi-Lagrangian* viewpoint ...
- Semi-Lagrangian methods: find source of tracer arriving at fixed grid locations

$$\int \frac{dF}{dt} = \frac{\partial F}{\partial t} + \frac{dx}{dt} \frac{\partial F}{\partial x} = 0 \quad \frac{dx}{dt} = U(x, t)$$

Semi-Lagrangian Properties-1

- Maximum Δt not limited by maximum wind speed
- Can stably integrate with Courant numbers > 1
- Can handle sharp gradients / discontinuities well
- But ... does not have conservation properties like finite volume methods
- Can be somewhat more expensive per time step

Semi-Lagrangian Properties-2

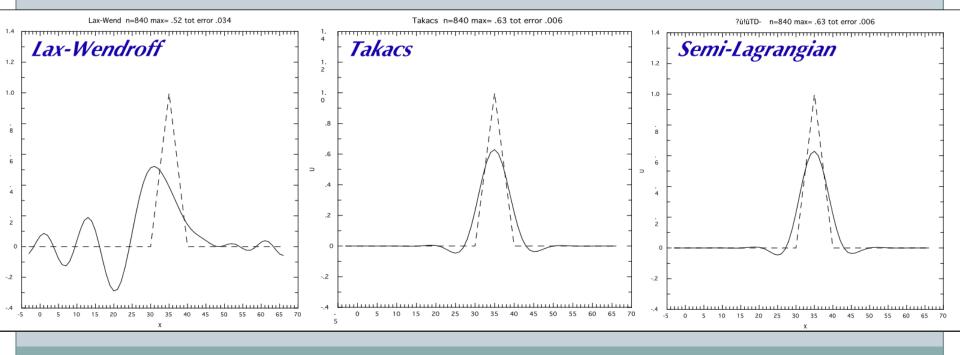
- Low dispersion
- Generally accurate but there is damping due to interpolation, though it is scale-selective.
- Important to limit <u>truncation errors</u> in
 - 1. discretized governing equations and
 - 2. in trajectory computations



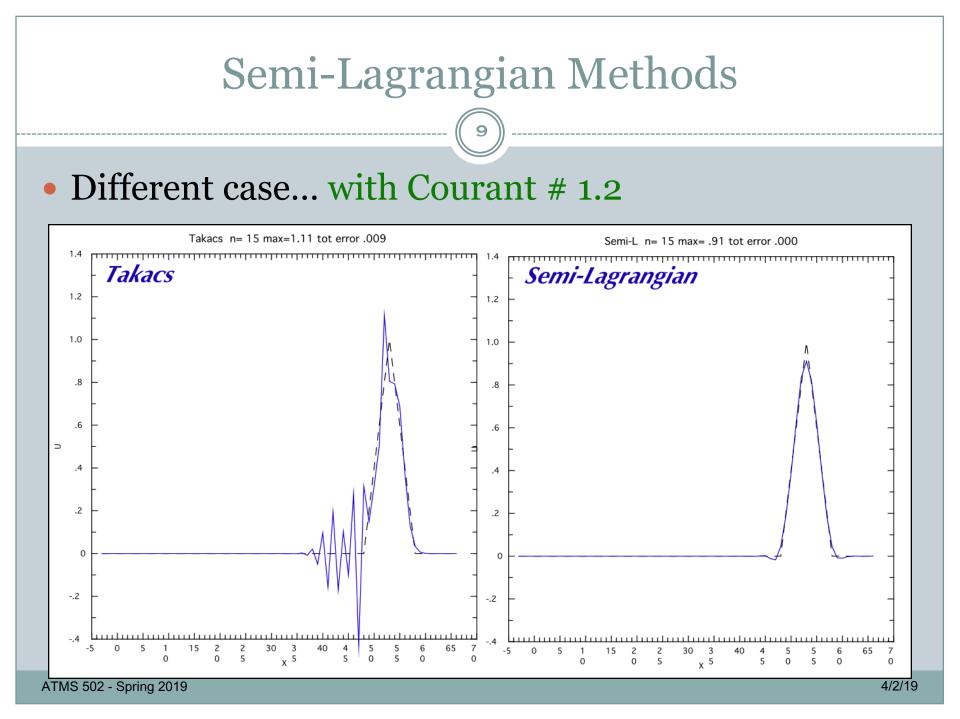
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Linear advection example

• 3 revolutions, courant number 0.25



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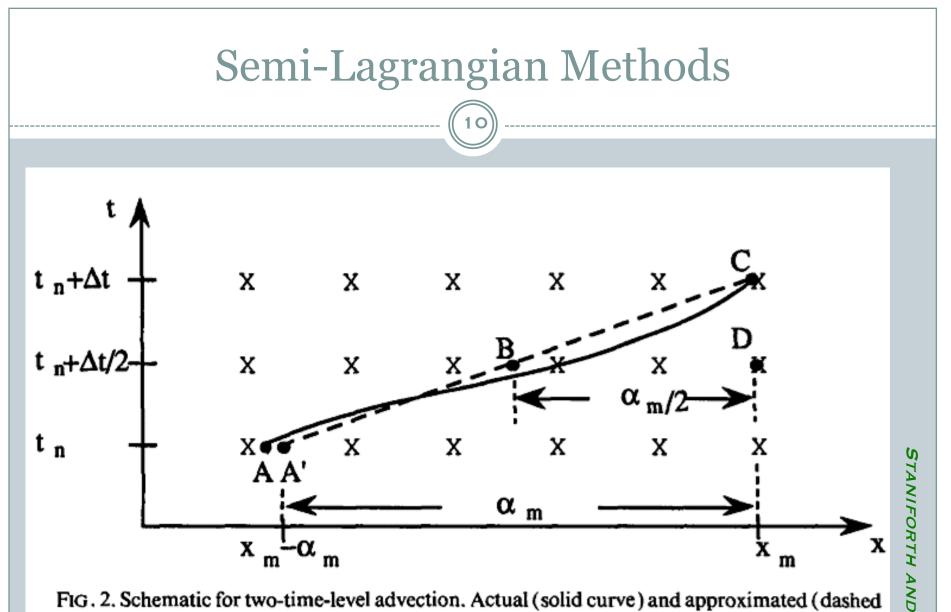


FIG. 2. Schematic for two-time-level advection. Actual (solid curve) and approximated (dashed line) trajectories that arrive at mesh point x_m at time $t_n + \Delta t$. Here α_m is the distance the particle is displaced in x in time Δt .

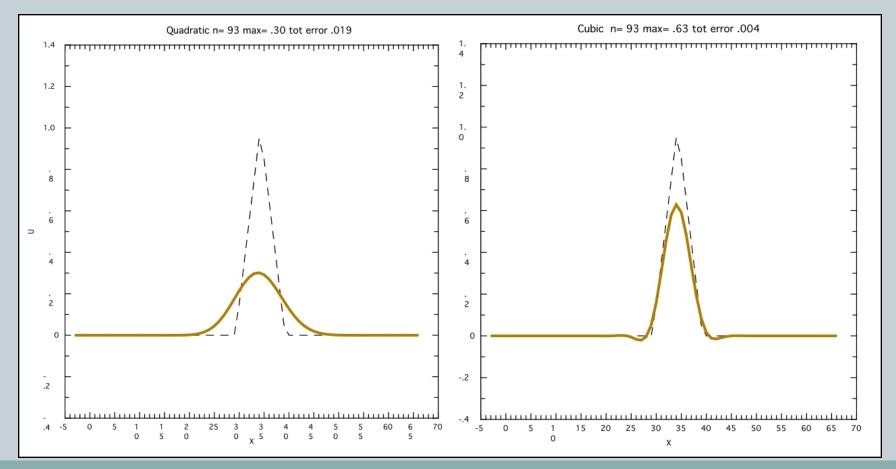
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Semi-Lagrangian Methods

• Interpolation matters.



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Semi-Lagrangian Methods

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• Staniforth and Cote, 1991, Mon. Wea. Rev.



Program #5

2D NONLINEAR, COMPRESSIBLE FLOW

13)

Program 5: Overview

• We are modeling nonlinear compressible flow.

- o nonlinear: time-evolving flow fields
- o compressible: well, *quasi*-compressible.
 - × there are sound waves
 - × we will *set* the sound wave speed C_s (300 m s⁻¹ = full speed)
 - × the only explicit density in our equations is a function of z, only.

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• Everything starts with temperature (θ)

- we specify up to *two* temperature perturbations.
- *perturbation* (potential) temperature = $\theta \overline{\theta}$
 - × with $\overline{\theta}$ = 300 (a constant). When plotting θ , always plot $\theta \overline{\theta}$.
- Change θ > P changes > U and W respond.
- Initial conditions: Specify initial θ ; initial U,W,P' = zero.

Program 5: Structure, BCs, base state

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General program structure

- o input
- o time loop
 - × start array update: $u_3=u_1$, etc.
 - × call BC routine
 - × call main physics subroutines
 - advection
 - o diffusion
 - o pgf
 - 🗴 array update

o on to the next step

• Boundary conditions

- Symmetric
- Periodic
- o Zero-gradient
- o "Slip"
- "Base state"
 - Only base state variable you *use*: density (1-D)
 - Pressure perturbation?
 - θ/temperature perturbation?

Program 5: Organization

We'll group functions by physical process Each physical process: One subroutine

o (1): *advection* routine will

× handle θ advection via calls to your *advect1d* routine, as before

▲ advection will also handle advection of U, W.

o (2): *diffusion* routine will

× carry out all diffusive terms, involving θ , U, W

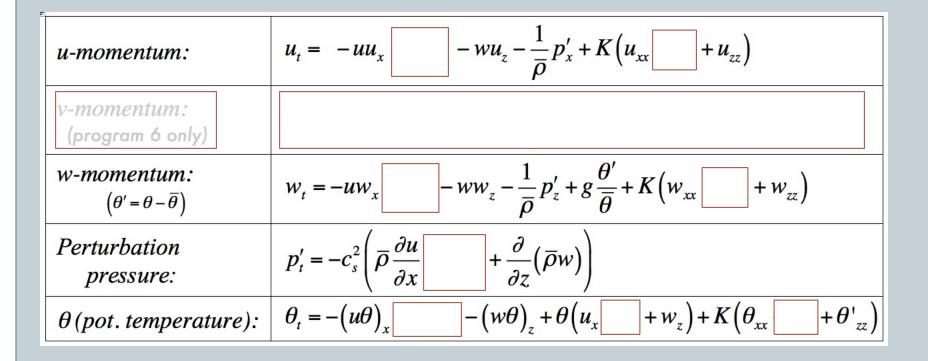
- (3): **PGF** routine handles all terms involving pressure
 - × PGF = pressure gradient force
 - × This routine will do the final contributions to U, W
 - × These new (u3, w3) terms are used to find the new P', p3.

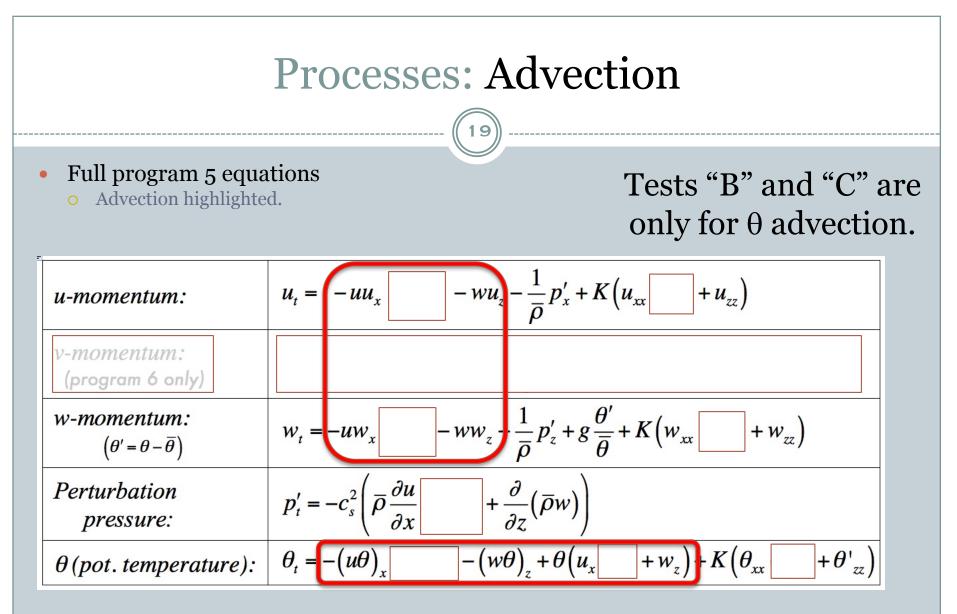
Program 5: 2D continuous equations

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• Full program 5 equations

 \circ all v terms and y-derivatives are ignored.



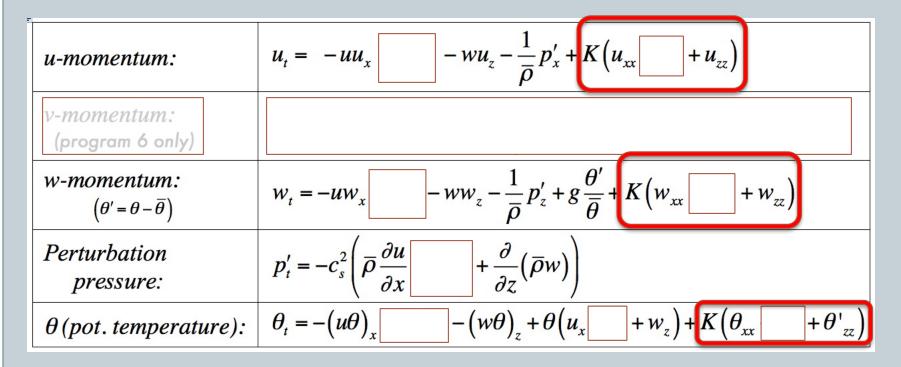


"advection" routine now includes *u*, *w* (nonlinear)

Processes: Diffusion

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- Full program 5 equations
 - Diffusion highlighted.



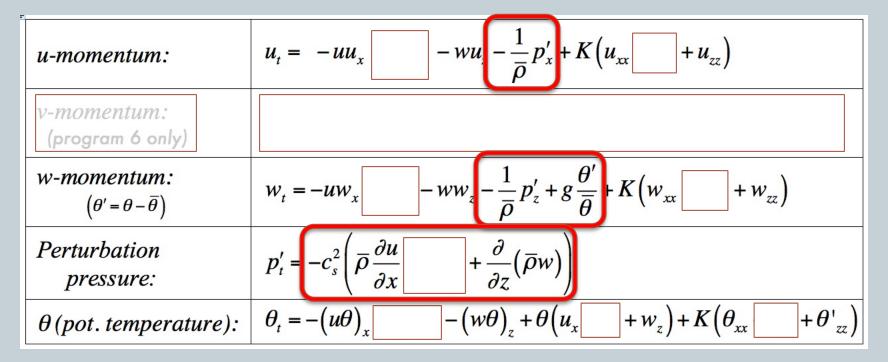
"diffusion" evaluates derivatives at (*n*-1) for u & w; (*n*) for θ

Processes: PGF+buoyancy

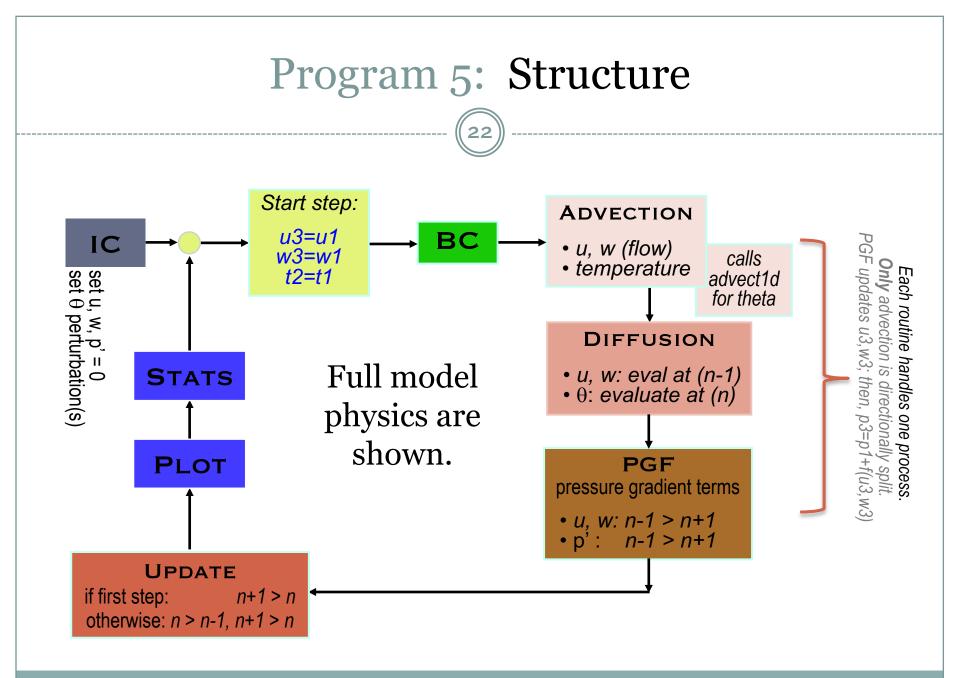
• Full program 5 equations

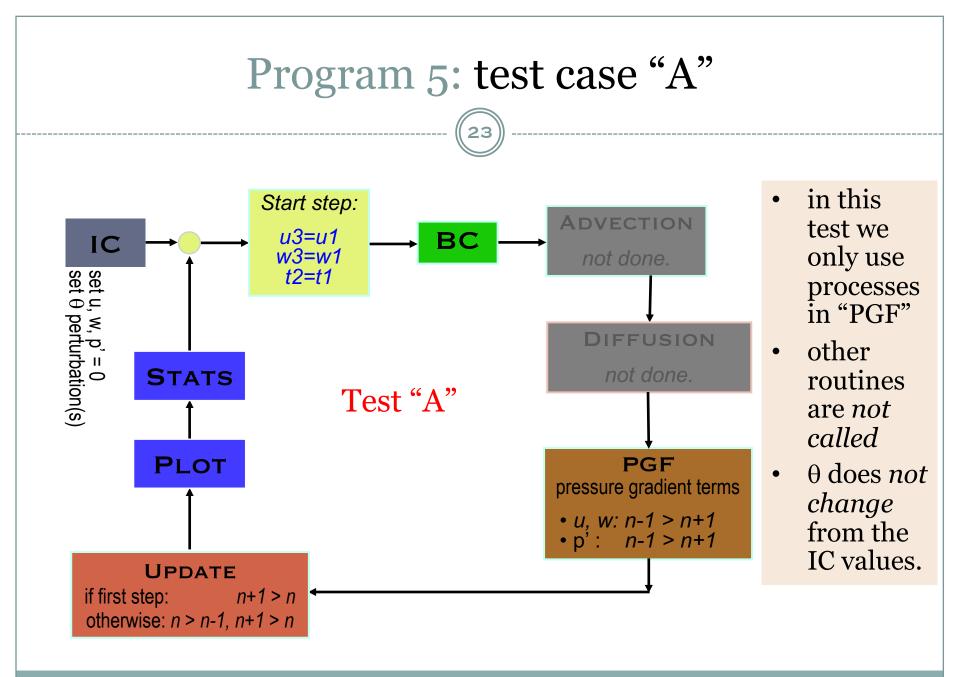
• pressure gradient & buoyancy highlighted.

This is **test "A"**



u3 = u3 + ...; w3 = w3 + ...; *set u, w BCs*; p3 = p1 + ...





Program 5: Dimensions

• Array dimensions

- ο Theta (θ) is treated as before, except ...
 - × we have added a dissipation term
- Your 2-D arrays : $NX \neq NZ$!!!
- You have additional 2-D arrays now that we are **nonlinear**:
 - × arrays for U, W are now time-evolving and need ghost zones!
 - **new array: P** (for perturbation pressure. needs ghost zones too)

• New 1-D arrays

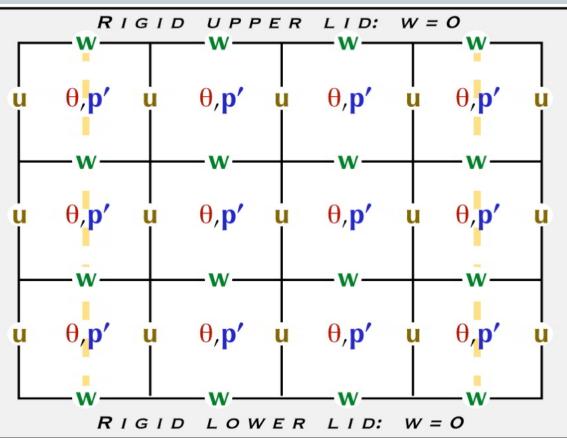
- \times for density at *theta/u/p levels* (altitudes)
- for density at *w-levels* (in-between those for theta/u/p)
 this density is **not** time-varying. Set it only once...
- × other arrays are used as part of initialization
 - and are never needed again.

Program 5: BCs

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Boundary conditions (B.C.'s)

• Z: B.C.'s as before RIGID × zero-gradient (w: zero @ top, bottom) θ,**p'** u u • X: BCs **symmetric** B.C.'s W o for W, P, θ **θ,p**′ u U **asymmetric** in X • only for U W



Program 5: Time integration

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Inside main program

- Before integration loop:
 - \times tstep = Δ t

• Main integration loop, near top:

- × t2 = t1
- \times u3 = u1
- \times w3 = w1
- call subroutines advection, diffusion, pgf

• Inside subroutines advection, diffusion, pgf

*t*² = *t*² + ∆*t* • [forcing terms] *u*³ = *u*³ + tstep • [forcing terms] *w*³ = *w*³ + tstep • [forcing terms]

• Remember:

- Theta is forward-time
- Everything else is centered-time

This is the first part of $u^{n+1} = u^{n-1} + tstep^{*}terms \dots$

Program 5: Update

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• Inside main program

o Update step, bottom of integration loop

if (this was the first time step)

u2 = u3	copy n+1 data over (replacing) "n" array
w2 = w3	copy n+1 data over (replacing) "n" array
p2 = p3	copy n+1 data over (replacing) "n" array
t1 = t2	copy n+1 data over (replacing) "n" array
$tstep = 2 \cdot \Delta t$	from now on, take $2\Delta t$ steps.

x otherwise (time step 2 onwards)

u1 = u2; u2 = u3	<i>copy n</i> > <i>n</i> -1, <i>and n</i> +1 > <i>n</i>
w1 = w2; w2 = w3	<i>copy</i> $n > n-1$ <i>, and</i> $n+1 > n$
p1 = p2; p2 = p3	<i>copy n</i> > <i>n</i> -1, <i>and n</i> +1 > <i>n</i>
t1 = t2	theta is forward time, always

Review: Program 5 coding

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• Changes and additions for:

- o initial condition routine
 - × no spatial variation specified for wind (or pressure)
 - × multiple perturbations for theta
- o boundary condition routine
 - × two dimensions: edges
- o main time step loop: starting
 - seginning the leapfrog time step; preparing theta
- o main time step loop: finishing
 - × switching from forward to leapfrog time
- routines
 - * advection, diffusion, and pgf (pressure-gradient-force/buoyancy)

Program 5: Questions

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Ghost points – when? where?

- To simplify things for myself I dimensioned almost everything 0:nx+1, 0:ny+1, i.e. one ghost point.
- But what is really needed ? *discuss 1-D, 2-D*

• Official case not yet ready

o yes.

- "nx" and "nz" refer to what variable? *theta* (potential temperature) and p (perturbation pressure).
- Grid points or cells?
 - o yes. Consider as points except in context of Piecewise Linear method
- What limits of arrays? *discuss*
- Diffusion: X, Z, both, how? discuss
- Strang splitting not yet

Program 5: Coding practice

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• Starting a time step

- Before doing anything else:
 - × t2 = t1
 - \times u3 = u1
 - \times w3 = w1

This also lets us turn processes on or off – we have taken the 'first part' of each time step – before starting.

× All later routines *add to* these "n+1" arrays.

• So in advection, diffusion, PGF, you will code ...

× $t2 = t2 + ... \Delta t \cdot [forcing terms]$ × $u3 = u3 + ... 2\Delta t \cdot [forcing terms] (same for W)$

• Exception: pressure

× Only one step to pressure: $p_3 = p_1 + 2\Delta t \cdot [forcing terms]$

Program 5: First time step

• Straightforward coding would look like ...

- Forward step:
 - $\mathbf{u2} = \mathbf{u1} + \Delta \mathbf{t} \bullet [forcing terms]$
- Centered step:
 - \times **u3** = **u1** + 2 Δ t [forcing terms]
- Writing all that code out twice is annoying.
- Instead, we will do ...
 - For the first time step, $tstep = \Delta t$; otherwise, $tstep = 2\Delta t$
 - And so our equations look like ...
 - × u3 = u1 + tstep [forcing terms] (same for W, P)
 - works because we also initialize our arrays u1=u2=0 (same for W, P)
 - *Except* for the temperature: θ is *always* forward in time.

Program 5: Where do I start?

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- Suggested order of development for Program 5
 - Modify program 2 or 3 code to everywhere to assume NX \neq NZ
 - Change physical dimensions; domain no longer [-0.5 :+0.5]
 - Create initial θ field, plot θ θ ; verify it looks OK.
 × So the initial θ plot will look like a circular field surround by zeroes
 - Set up all arrays:
 - × u, w, p: three time levels, 2-D
 - × t: two time levels, 2-D
 - \times density (for p/t/u levels) and density for w-levels: 1-D
 - Create initial 1-D base-state fields for density
 - Create routine for boundary conditions
 - **Test** in this order: *PGF*; *linear* θ *advection* θ ; θ *diffusion*.
 - Now: full physics.