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ATMS 502
CSE 566

Thursday,
28 February 2019

Class #14

• Pgm3 due Wed Mar. 6

Plan for Today

2/28/19

- 1) Time filtering
 - Damping leapfrog's computational mode
- 2) Grid refinement & clustering
 - Skamarock dissertation (notes: last class)
- 3) Program 4: *provided codes*
 - Placing/moving nest, & feedback
- 4) Resolution
 - Resolved/*permitted*; KE spectra method
- 5) Nesting, continued
 - Some questions & answers

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Leapfrog stability - review

- We rewrote the 3-level scheme as 2-level:

$$\begin{matrix} \tilde{u}^{n+1} = \tilde{v}^n - i\tilde{u}^n(2i\sin\beta) \\ \tilde{v}^{n+1} = \tilde{u}^n \end{matrix} \text{ so } \begin{pmatrix} \tilde{u}^{n+1} \\ \tilde{v}^{n+1} \end{pmatrix} = \begin{pmatrix} -2i\mu\sin\beta & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \tilde{u}^n \\ \tilde{v}^n \end{pmatrix}$$
- Write above as matrix, subtract I from diagonal, set determinant to zero. Characteristic equation:

$$\begin{vmatrix} -2i\mu\sin\beta - \lambda & 1 \\ 1 & 0 - \lambda \end{vmatrix} = 0$$
- Solve; 2 roots; physical and computational modes

$$\lambda = -i\mu\sin\beta \pm \sqrt{1 - \mu^2\sin^2\beta} = -ip \pm \sqrt{1 - p^2}$$
- As Δt and $p \rightarrow 0$: "+" root approaches 1, "-" root: -1
 - $|\lambda| = -1$ means amplitude varies as $(-1)^n$

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Review: 1-D Nesting

- Interpolation: *old vs. new nested grids*

Old nest

new nest

THIS EXAMPLE:
3:1 NESTING
- Feedback: *copy nested => coarse*

J=4

J=1

THIS EXAMPLE:
4:1 NESTING

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Time filtering

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LEAPFROG TIME+SPACE DIFFERENCING
PHYSICAL AND COMPUTATIONAL MODES
UNDAMPED COMPUTATIONAL MODES
TIME FILTERING: WHY, AND HOW TO?

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Time-filtered Leapfrog

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- **Advantages** of the Leapfrog method:
 - Stable, 2nd order
 - Simple, & thus computationally cheap
 - ✦ but little computation for amount of communication
 - ✦ this is true for other schemes we have examined, too.
 - No amplitude error (if stable)
- **Disadvantages:**
 - Undamped **computational mode**
 - ✦ How to find the physical vs. computational mode
 - ✦ What is an *undamped* computational mode?
 - ✦ Odd/even solutions; may diverge
 - Dispersion, etc (*not unique to leapfrog*)

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Time-filtered Leapfrog

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- **How to control the computational mode?**
 - Periodically discard (n-1) time level data
 - Restart integration with a 2-level scheme
 - ✦ Common practice: **FTCS** scheme (*forward time, centered space*)
 - ✦ ... but **FTCS** is unstable, and
 - ✦ ... **FTCS** is 1st order (degrades accuracy)
 - ✦ Or: use **Upstream** or **Lax-Wendroff**
- **Time smoothing**
 - Remember computational mode: $\lambda \sim (-1)^n$
 - Smooth across (n-1, n, n+1) time levels

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Time-filtered Leapfrog

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- **Time smoother for Leapfrog (Asselin 1972)**
 - Instead of:

$$u_j^{n+1} = u_j^{n-1} - \mu(u_{j+1}^n - u_{j-1}^n)$$
 - Time smoothing:

$$\begin{aligned} u_j^{n+1} &= u_j^{n-1} - \mu(u_{j+1}^n - u_{j-1}^n) && \text{(LEAPFROG STEP)} \\ \bar{u}_j^n &= u_j^n + \epsilon(u_j^{n+1} - 2u_j^n + u_j^{n-1}) && \text{(SMOOTHING STEP)} \end{aligned}$$
 - Stable if $\mu < (1-\epsilon)$
 - ✦ So there is a more restrictive stability condition.

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Time-filtered Leapfrog

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- Time smoother for Leapfrog (Asselin 1972)

$$\overline{u_j^{n+1}} = \overline{u_j^{n-1}} - \mu(u_{j+1}^n - u_{j-1}^n) \quad (\text{LEAPFROG STEP})$$

$$u_j^n = \overline{u_j^n} + \epsilon(u_j^{n+1} - 2u_j^n + u_j^{n-1}) \quad (\text{SMOOTHING STEP})$$

- Sequence:**
 - Have: (n-1, smoothed) and (n, unsmoothed)
 - Take leapfrog step to get (n+1, unsmoothed)
 - Use new (n+1, unsmoothed) to smooth u(n)
 - Ready for next step [smoothed u => u(n-1)]

NOTES - HANDED OUT LAST CLASS!

Grid refinement & Clustering

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ADAPTIVE MESH REFINEMENT

Reference pages for this section:

- C008 - Truncation error
- C009 - Resolution
- C010 - AMR / nesting
- C051 - Nesting: grid placement, movement

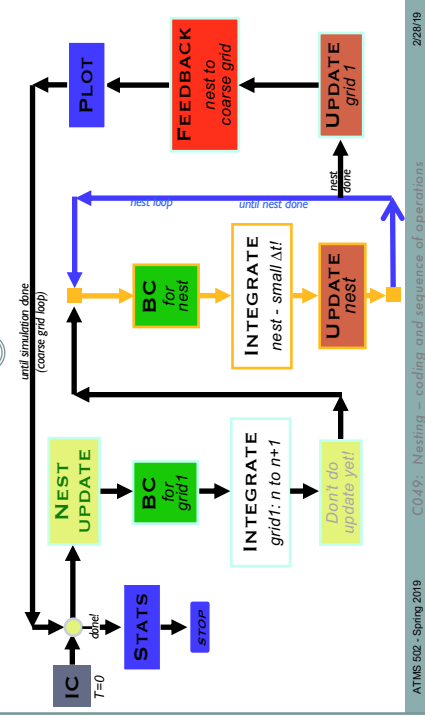
Program 4

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NESTING TOOLS PROVIDED TO YOU

Program #4: main routine

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Nest BCs

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- “Placing” the nest

Coarse grid w/moved nest

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Nest placed

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Nest BCs

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- Moving the nest

Nest moved

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Nest moved

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Nest BCs

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- Testing feedback

Coarse grid w/moved nest

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Coarse grid after feedback

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Resolution

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Resolving vs. permitting

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- **Feature-resolving** means what it says.
 - A model may instead have feature-**permitting** resolution
 - ✦ Means: those phenomena are “in” the model, e.g. via parameterizations and only in a very broad sense
 - Some models contain both **explicit** and **parameterized** physics
 - ✦ Explicit actually describes ~correct behavior – if really resolved
 - ✦ Parameterized reproduces bulk properties of the phenomena even though it is not resolved
 - ✦ Things get interesting in the *in-between* resolutions (“**gray scales**”)
- **Liu and Moncrieff (2007 Mon. Wea. Rev., p. 2866)**
 - **Cloud-permitting** runs “underperform” and exhibit greater **sensitivity** to parameterizations than the cloud-**resolving** models exhibit from their explicit physics.

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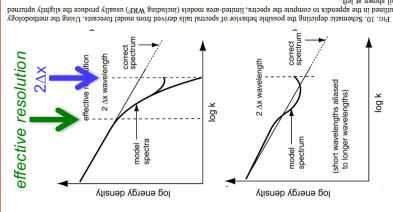
C.009: Resolution

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Effective resolution

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- **Skamarock (2004):**
 - Why move to higher resolution?
 - ✦ Typically this is done to resolve phenomena that are now marginally resolved, or unresolved (i.e. parameterized)
 - “Effective” resolution
 - ✦ There are known **kinetic energy spectra** profiles (see Skamarock Fig. 10 at right).
 - ✦ Models fail to reproduce these spectra at smaller scales. Note the dropoff at higher wavenumber (lower wavelengths)
 - ✦ He defines effective model resolution to be where the model spectra “decays”
 - WRF atmospheric model: $7\Delta x$ (p. 3027)



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C.009: Resolution

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Nesting

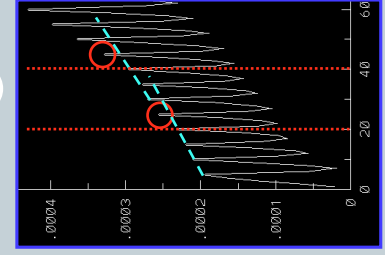
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Question 1: oscillations

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- Nest shock is superimposed on the high frequency oscillations seen here
- But: What causes oscillations?
- Total grid-1 error is plotted at each time step

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(21)

No, oscillations aren't due to *this*.

C023: Phase error

2/28/19

(22)

Question 1: oscillations

- How long does it take for features to move 1 Δx ???
 - $s=vt$; time = distance/speed; $t=s/v$
 - Total time to go distance $\Delta x = \Delta x/c$
 - # time steps to go $\Delta x = 1/v$ (why?)
- So, every 5 time steps ... (for $v=0.2$)
 - The cone peak moves one grid distance.
 - What does this say about our "true" solution?

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C043: Courant number

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(23)

Question: oscillations

(1) What are these oscillations?

- Every 5 time steps the (exact) solution moves one grid length.
- At right: 2 periods in 10 steps

C023: Phase error

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(24)

Question: oscillations

(1) What are these oscillations?

- Every 5 time steps the (exact) solution moves one grid length.
- At right: 2 periods in 10 steps

- Projecting an exact solution on a finite grid results in errors in the "true" solution !!

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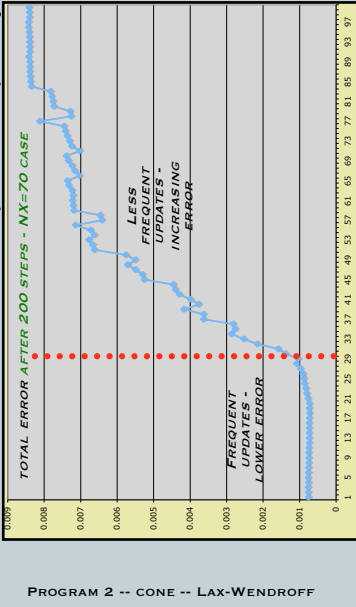
C043: Courant number

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Question 2: update frequency

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Below: error scores vs update frequency

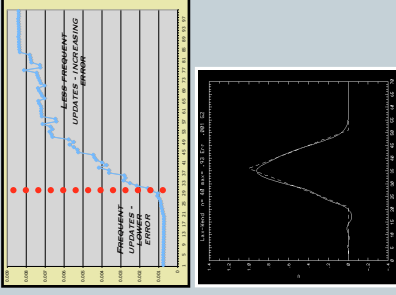


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Question 2: update frequency

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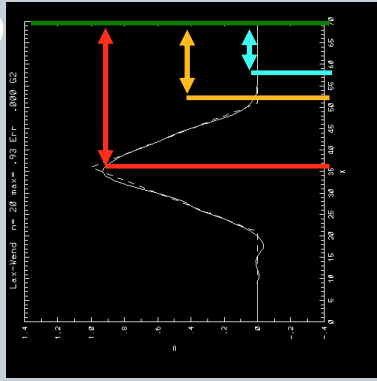
- Red dotted line is at ~30 (grid relocated every 30 steps).
- # steps for cone to move from center of nest to "center" of edge: $5 * (24/2) = 60$
- *What does this tell us?*

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Question 2: update frequency

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- In **60 steps** the middle of the cone is on the right nest domain edge.
- In **30 steps**, when the error starts rapidly rising, the right edge of the cone (and of trunc. error) hits the nest edge.
- In **20 steps**, the nest border is still ahead of the cone's leading edge.

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The CFL condition

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STABILITY - CONTINUED

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PDE classification: Two kinds

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$$Au_{xx} + Bu_{xy} + Cu_{yy} = F(x, y, u, u_x, u_y)$$

Details: F is a linear function of u, u_x, u_y ; coefficients may only depend on x, y . Subscripts are derivatives!

- Is **elliptic** if $B^2 - 4AC < 0$ Laplace's equation
- Is **parabolic** if $B^2 - 4AC = 0$ Heat equation
- Is **hyperbolic** if $B^2 - 4AC > 0$ Wave equation
- $B^2 - 4AC$ came from **characteristics**, or characteristic curves - curves of **information propagation**. The 2nd-order wave equation has the characteristics: $x \pm ct = \text{constant}$
- **Initial value problems** - the principal computational concern is the **stability** of the numerical algorithm/scheme.
 - PDE includes a time derivative!
- **Boundary value problems** - Involves solving solutions of large numbers of equations; **efficiency** is key concern.

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A011 - PDE type/classification; A012 - PDE characteristics

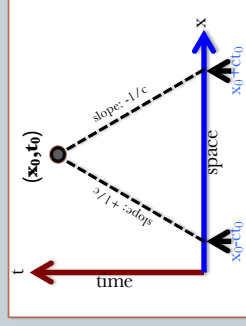
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Characteristics

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Hyperbolic case; characteristic curves

- Example: 2-D wave equation
- Two wave speeds: $\pm c$
- An initial value problem



Adapted from Figure 2.6 of Anderson et al., p. 23

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A012 - PDE characteristics; A014 - Domain of dependence

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CFL

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- The **CFL** (Courant-Friedrichs-Lewy) condition
 - "On the partial difference equations of mathematical physics"*
 - Based on the *data* that
 - determines the solution to the **actual PDE**
 - determines the solution in the **numerical scheme**
 - Requires that
 - the numerical domain of dependence must **include** the PDE domain of dependence.
- A **necessary but not sufficient** condition for stability.
 - The CFL criteria **need not agree** with the results of the Von Neumann analysis.

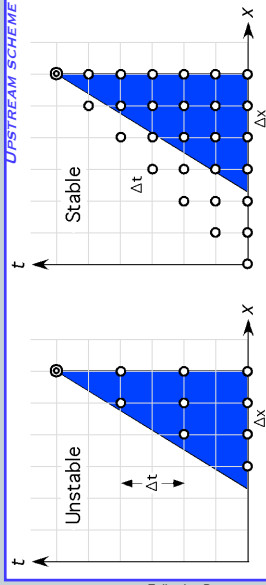
*Courant, R., K. O. Friedrichs, and H. Lewy (1928). "Über die Differenzengleichungen der Mathematischen Physik". *Math. Ann.* vol. 100, p. 32, 1928.

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Domain of Dependence

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- The CFL condition requires that the **numerical domain of dependence** include the **PDE domain of dependence**.



Following Durran, p. 46

Unstable case: true domain of dependence extends outside of numerical one.
Stable case: Δt halved; numerical domain contains true domain of dependence.

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