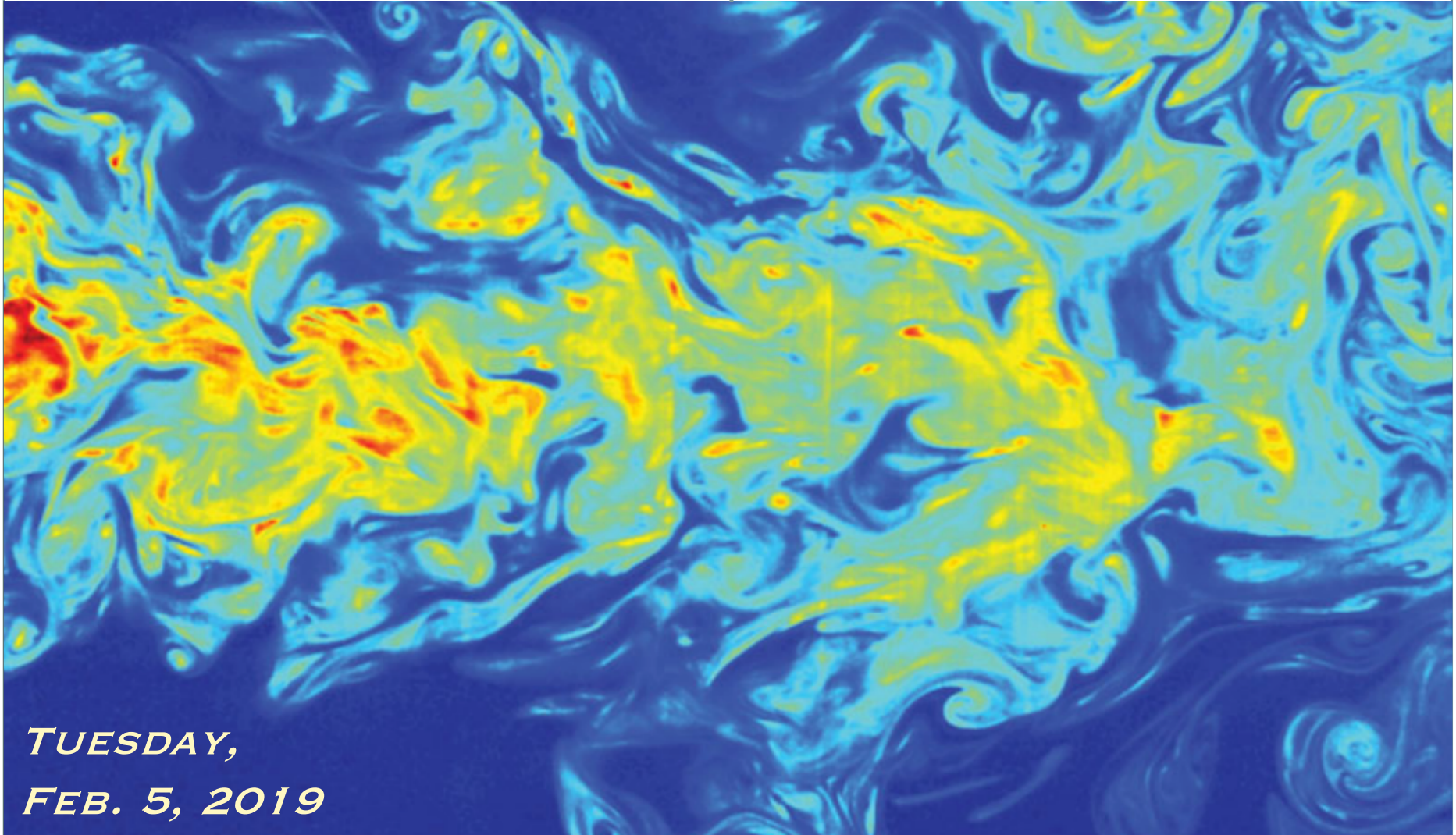


*Atms 502, CSE 566*

# *Numerical Fluid Dynamics*



*TUESDAY,  
FEB. 5, 2019*

ATMS 502  
CSE 566

Tuesday,  
5 February 2019

Class #7

*Homework #1*  
*prob #4 typo:*  
*should be*  
 *$2\Delta x$  not  $\Delta x$  !!*

## Plan for Today

- 1) REVIEW  
Takacs vs. Polar plots
- 2) NUMERICAL METHODS :
  - Stability, continued:
    - ✦ Norms; von Neumann's method
    - ✦ Apply to a numerical method
    - ✦ Operator definitions
  - Phase error
    - ✦ *wavelength-dependent phase speeds*
  - The modified equation
- 3) CODE/DATA:  
Program #2 - continued

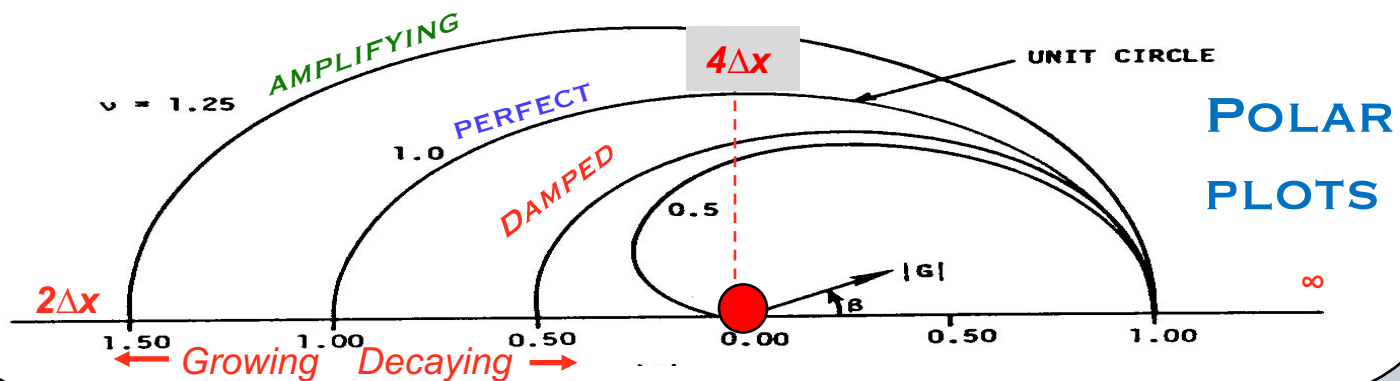
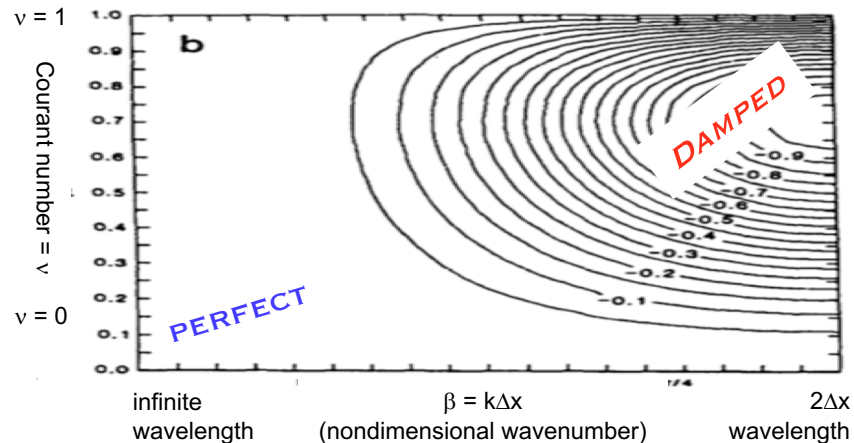
# Review: Plots of scheme behavior

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## AMPLITUDE

### TAKACS' PLOTS

(NOT SHOWING THE SAME NUMERICAL METHOD)



Anderson et al., chapter 4

# Stability

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## OBJECTIVES:

*DEVELOP THEORY AND METHODOLOGY  
FOR DETERMINING IF, HOW, AND WHEN A  
SCHEME HAS SATISFACTORY STABILITY.*

*FOLLOWING NOTES HANDED OUT IN LAST CLASS !!*

### References:

- A009 – Instability (physical)
- C015 – Instability (numerical)

# Operator definitions

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USED FOR REMAINDER OF CLASS

***FOLLOWING NOTES HANDED OUT IN LAST CLASS !!***

# Dispersion & phase error

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IN CONTEXT OF: FOURIER SERIES

## References:

- Co16 – Fourier series
- Co23 – Dispersion
- Co33 – Gibbs phenomenon

# Fourier series

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- Assuming we have a *periodic* function of period  $2\pi$ , we can represent it with the following trig series:

$$f(x) = a_0 + \sum_{n=1}^{\infty} (a_n \cos nx + b_n \sin nx)$$

- Solve using the *Euler Formulas*:

Period = T  
↙

$$\left. \begin{aligned} a_0 &= \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx \\ a_n &= \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos(nx) dx \\ b_n &= \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin(nx) dx \end{aligned} \right\} n = 1, 2, \dots$$

OR

$$\left. \begin{aligned} a_0 &= \frac{1}{T} \int_{-T/2}^{T/2} f(t) dt \\ a_n &= \frac{2}{T} \int_{-T/2}^{T/2} f(t) \cos \frac{2n\pi t}{T} dt \\ b_n &= \frac{2}{T} \int_{-T/2}^{T/2} f(t) \sin \frac{2n\pi t}{T} dt \end{aligned} \right\} n = 1, 2, \dots$$

# Fourier series

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- Let's look at the representation of a square wave.

$$f(x) = \begin{cases} -k & \text{when } -\pi < x < 0 \\ k & \text{when } 0 < x < \pi \end{cases}$$

- The analytical solution turns out to be:

$$\left. \begin{array}{l} a_0 = 0 \\ a_n = 0 \\ b_n = \frac{4k}{n\pi} \end{array} \right\}, n = 1, 3, 5 \dots \text{ such that } f(x) \approx \frac{4k}{\pi} \left( \sin x + \frac{1}{3} \sin 3x + \frac{1}{5} \sin 5x + \dots \right)$$

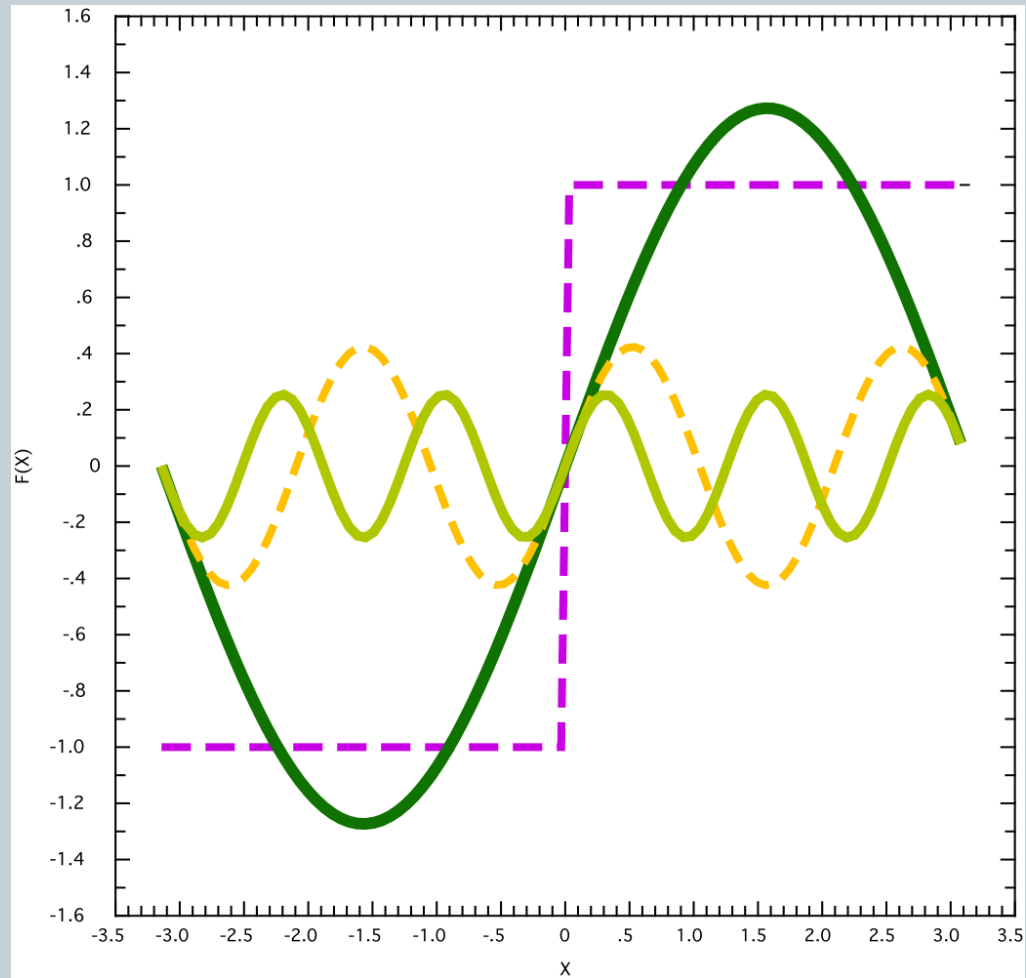


# Fourier series & square wave

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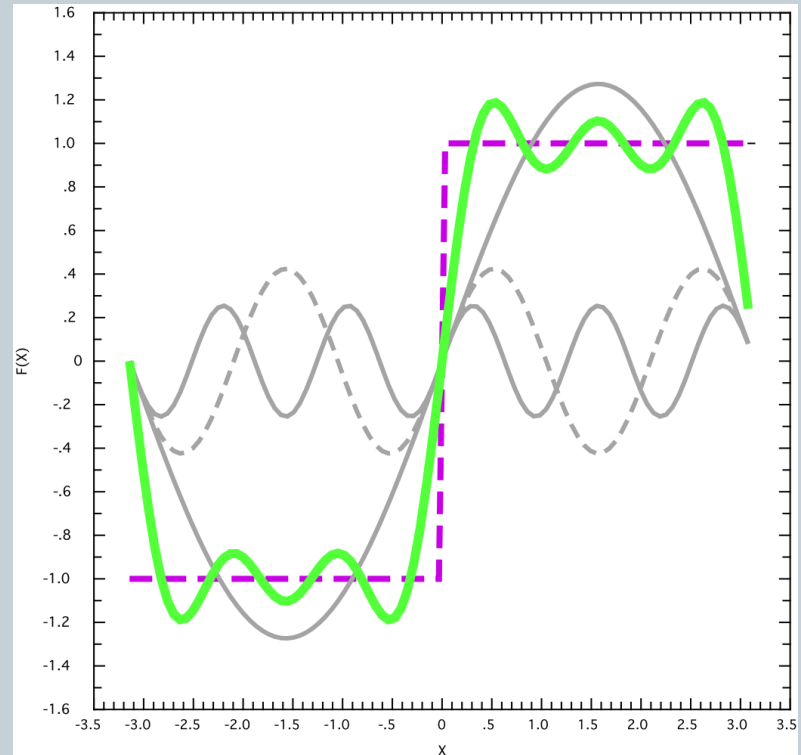
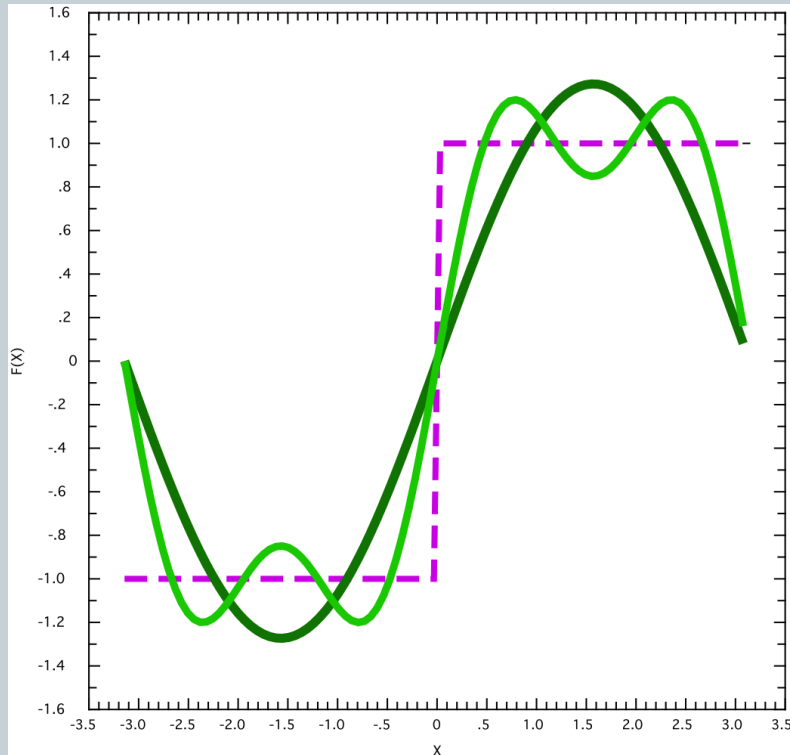
- Fourier series *cannot be used (with the strict equality) for a discontinuity; doing so invokes the **Gibbs phenomenon**.*
- “While the rms error of the Fourier series goes to zero for an infinite number of terms, equality at every point is not guaranteed; *the Gibbs phenomenon peaks have finite height and zero width.*”
- Coefficients in a truncated Fourier series can be used to reduce or eliminate the Gibbs effect; see References for more on these windowing methods.

- $N=1,3,5$ :  
three  
waves  
shown:  
 $\sin(x)$ ,  
 $\sin(3x)$ ,  
 $\sin(5x)$  ...



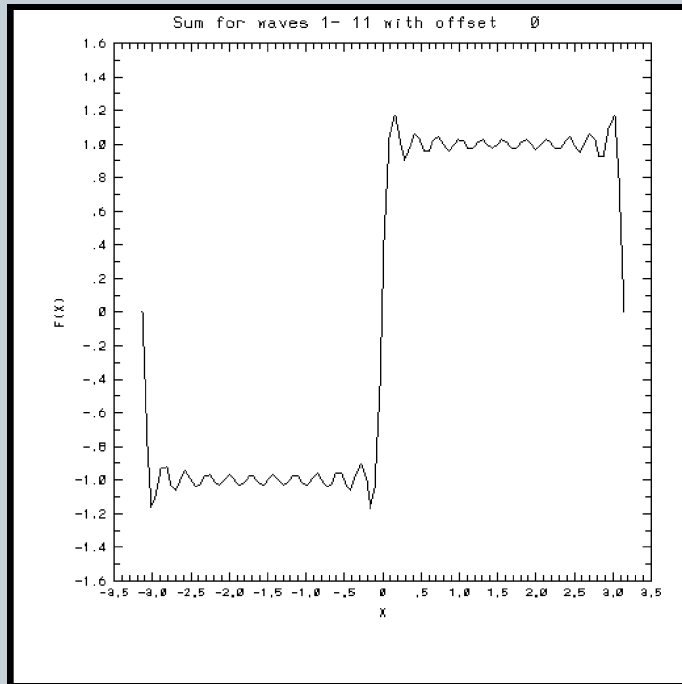
- Using one wave vs. sum of two waves

- Sum of first three waves. • A better approximation.



# What if our scheme has phase errors?

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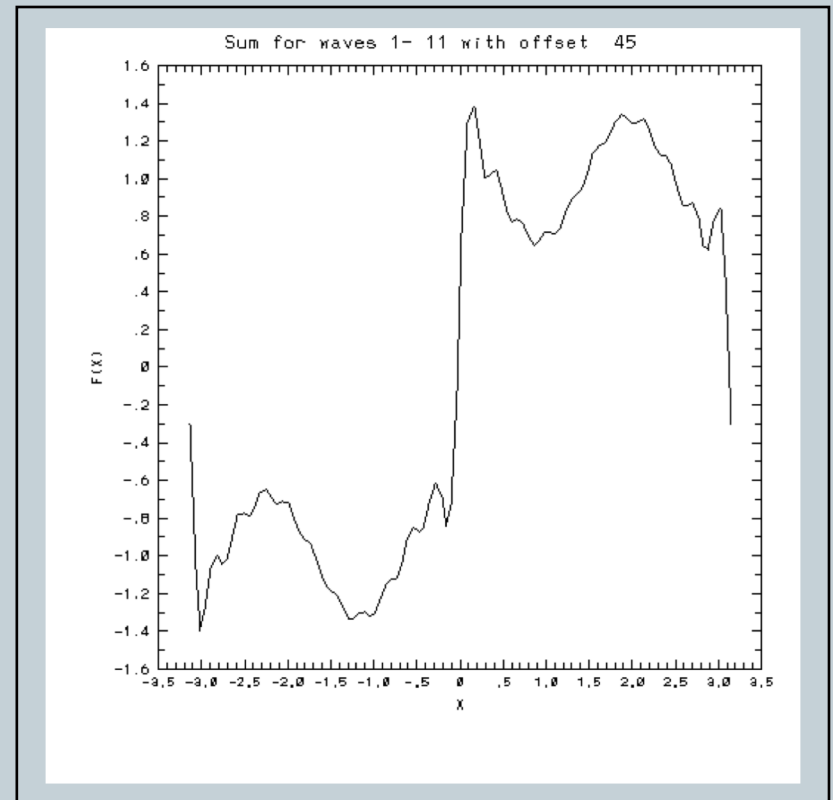
- *In this example, there is no phase shift - we add the terms correctly.*

- We'll take *one component - 1 harmonic* - and change it
- The second wave -- with *wave number  $k=3$*  -- will have a *phase shift* added to it.
- There are 11 contributing waves; all other components - the other 10 waves - will remain the *same*.

# Phase errors

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- Dispersion distorts the solution by introducing **wavenumber-dependent phase errors**
- The **phase relationship** between the different wave components is changed.
- In this example, the 2<sup>nd</sup> wave component was shifted by **+45°**



# The modified equation

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**WHY** WE SEE CHARACTERISTIC  
(OR REALLY, DOMINANT)  
ERRORS FOR TYPES OF SCHEMES

# The modified equation

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- Upstream scheme - truncation error:

$$u_t + cu_x = -\frac{\Delta t}{2}u_{tt} + \frac{c\Delta x}{2}u_{xx} + \text{higher order terms} \quad (1)$$

- To say more about this scheme, we want the right side to be in terms of **X derivatives**, *only*.

- Take equation (1), and take **d/dt**:

$$u_{tt} + cu_{xt} = -\frac{\Delta t}{2}u_{ttt} + \frac{c\Delta x}{2}u_{xxt} + \text{higher order terms} \quad (2)$$

- And now take **-c•d/dx** of (1):

$$-cu_{tx} - c^2u_{xx} = \frac{c\Delta t}{2}u_{ttx} - \frac{c^2\Delta x}{2}u_{xxx} + \text{higher order terms} \quad (3)$$

Now: add  
(2) + (3) ...  
for  $u_{tt} = \dots$

# Modified equation: implicit viscosity

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- Our original equation:

$$u_t + cu_x = -\frac{\Delta t}{2}u_{tt} + \frac{c\Delta x}{2}u_{xx} + \text{higher order terms} \quad (1)$$

- Our expression for  $u_{tt}$  was:

$$u_{tt} = c^2u_{xx} + \Delta t\left(-\frac{u_{ttt}}{2} + \frac{c}{2}u_{ttx} + \dots\right) + \Delta x\left(\frac{c}{2}u_{xxt} - \frac{c^2}{2}u_{xxx} + \dots\right) \quad (4 = (\text{eq. 2}) + (3))$$

- Substituting, we get:

$$u_t + cu_x = \frac{c\Delta x}{2}(1 - \nu)u_{xx} + (\dots)(\Delta x)^2u_{xxx} + \text{higher order terms}$$

- This is the *modified equation*
- It is what is *actually solved* by the F.D. method
- $U_{xx}$  term: “*implicit*” *artificial viscosity!* (not an implicit numerical method!)



# Modified equation: dissipative errors

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- Modified equation:

$$u_t + cu_x = \frac{c\Delta x}{2}(1 - \nu)u_{xx} + (\dots)(\Delta x)^2 u_{xxx} + \text{higher order terms}$$

- Why is this diffusive?

- Recap: we started with a *hyperbolic* PDE,  $u_t + cu_x = 0$ .
- The modified equation tells us what we *really* solving.
- Now our analysis reveals terms like:  $u_t = (\dots) \cdot u_{xx}$ 
  - ✦ This is a parabolic equation!
    - wait, weren't we solving a *hyperbolic (transport)* equation?
  - ✦ Parabolic > for example, heat transfer
    - Bottom line: Dissipation!

# Diffusive upstream method: polar plot

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- **Modified equation** for the upstream method:

$$u_t + cu_x = \frac{c\Delta x}{2}(1 - \nu)u_{xx} + (\dots)(\Delta x)^2 u_{xxx} + \text{higher order terms}$$

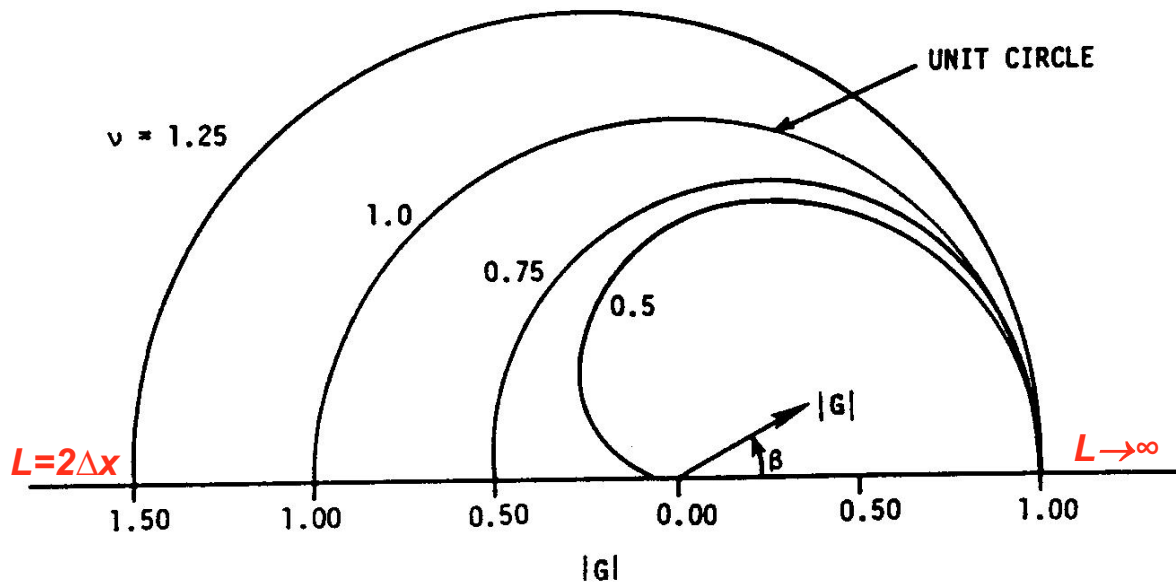


Figure 4-2 Amplification factor modulus for upstream differencing scheme.

# Shift condition

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- **Modified equation** for the upstream method:

$$u_t + cu_x = \frac{c\Delta x}{2}(1 - \nu)u_{xx} + (\dots)(\Delta x)^2 u_{xxx} + \text{higher order terms}$$

- **What if** the Courant number  $\nu=1$  here?
  - The  $u_{xx}$  term on the right side of the modified equation disappears
  - In fact, we know this scheme has a *shift condition* when the Courant number  $\nu=1$ .
    - ✦ this means the solution is shifted one grid point per time step.

$$u_j^{n+1} = u_j^n - \nu(u_j^n - u_{j-1}^n) ; \nu = \left(\frac{c\Delta t}{\Delta x}\right)$$

# Problems with upwinding-type schemes

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- Note the **problem with upstream-type methods**:

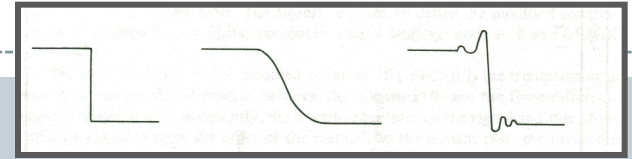
$$u_t + cu_x = \frac{c\Delta x}{2}(1 - \nu)u_{xx} + (\dots)(\Delta x)^2 u_{xxx} + \text{higher order terms}$$

- The implicit diffusion  $u_{xx}$  from this scheme is **dependent on the local flow speed**.
  - So you have uneven damping throughout your flow
  - Some modelers rely on this *implicit*\* damping to stabilize their solution. We'll return to this later.

\*Again, *implicit* here refers to the damping, not an implicit numerical method.

# Summary: Errors vs. order of accuracy

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- Explicit artificial viscosity
  - An added term in a difference equation *designed* to add damping
- Implicit artificial viscosity
  - Unphysical damping as a *consequence* of the finite difference scheme
- Summary of error properties
  - Dispersion - **distortion of waves** as a result of odd derivative terms in the truncation error - even order accuracy!
  - Dissipation - **reduction of gradients** as a result of even derivative terms in the truncation error - odd order accuracy!
  - Diffusion: combined effect of dissipation and dispersion

# Convergence

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## We've discussed:

- Finite difference approximations to derivatives
- Truncation error
  - Taylor series
  - Order of accuracy
- Consistency
- Stability
  - Von Neumann's method
  - CFL

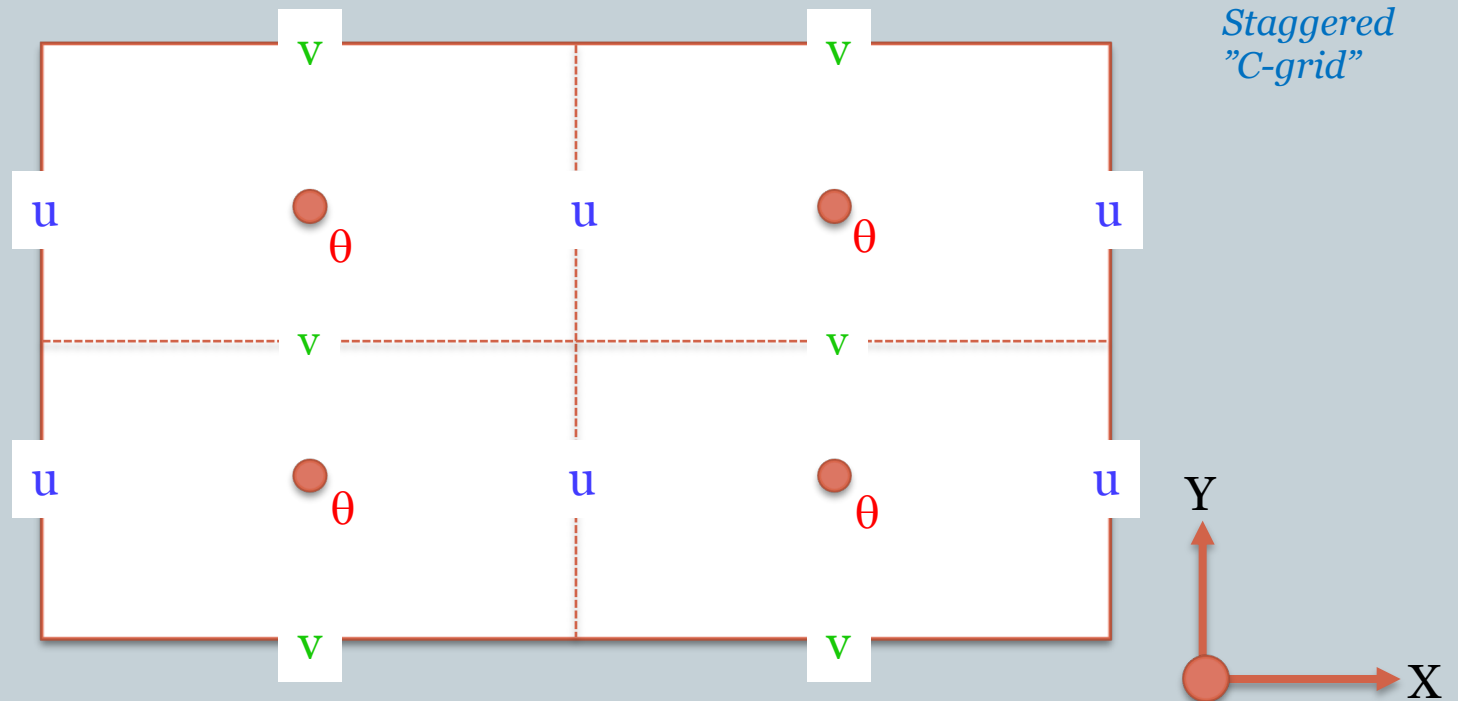
## Convergence -

### Lax equivalence theorem

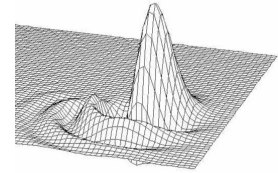
- If a finite difference scheme is:
  - Linear
  - Stable
  - Accurate of order  $(\Delta t)^p, (\Delta x)^q$ , then
- It is **convergent** of order  $(p,q)$ 
  - *This has not been shown to apply to nonlinear PDE's !!*
  - *Durran, §2.1.3, p. 40*

# Computer Program 2

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# Program 2: Advection



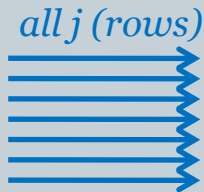
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## • Advection

- I set up 1-D arrays in my advection routines –
  - ✦  $q1d(0:nx+1)$ ,  $u1d(nx+1)$ ,  $v1d(ny+1)$  *no ghost points for U, V !!*

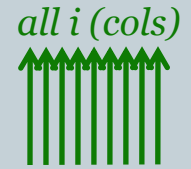
## • Advecting rows (X)

- copy  $q1(i,j)$  to  $q1d$
- copy  $u(i,j)$  to  $u1d$
- pass  $q1d$ ,  $u1d$  to *advect1d*
  - ✦ *advect1d* returns  $q1d\_out$
- copy  $q1d\_out$  to  $q1(i,j)$



## • Advecting columns (Y)

- copy  $q1(i,j)$  to  $q1d$
- copy  $v(i,j)$  to  $v1d$
- pass  $q1d$ ,  $v1d$  to *advect1d*
  - ✦ *advect1d* returns  $q1d\_out$
- copy  $q1d\_out$  to  $q1(i,j)$



discuss: how many 2D  $q()$  arrays here?